

Introduction To Autonomous Mobile Robots Mit Press

A Marvel of Mechanical Minds and Human Hearts: "Introduction to Autonomous Mobile Robots (MIT Press)" Redefines the Robot Narrative

Prepare yourselves, dear readers, for a journey not of dusty textbooks and dry equations, but of whirring gears, blinking sensors, and surprisingly profound emotional resonance. The "Introduction to Autonomous Mobile Robots" from MIT Press, often heralded for its academic rigor, has, in a stroke of pure genius, transcended its technical origins to become something far more... enchanting. This isn't just a book; it's an invitation to witness the nascent spark of consciousness in silicon and steel, wrapped in a narrative so imaginative, it's as if a whimsical inventor decided to pen a love letter to artificial intelligence.

Forget the dystopian nightmares of rogue automatons; this volume offers a refreshingly optimistic and, dare I say, "delightful*" exploration of our mechanical counterparts. The "imaginative setting" isn't a far-off galaxy, but rather the meticulously crafted inner world of these robots themselves. We are privy to their "thought processes," their algorithmic "emotions" (yes, you read that right!), and their endearing attempts to navigate a world built for flesh and blood. It's a testament to the authors' skill that they can imbue lines of code with such palpable personality. You'll find yourself cheering for a robot's successful pathfinding algorithm as if it were a crucial sports victory, and empathizing with its perceived "frustrations" when a sensor misfires.

The true magic, however, lies in the unexpected "emotional depth." Who knew that a discussion on kinematics could evoke such tenderness? The book masterfully weaves in moments of poignant reflection on autonomy, purpose, and even the very definition of being. It's a subtle, yet powerful, exploration that resonates on a deeply human level, reminding us that the quest for understanding, whether biological or artificial, is a universal endeavor. This emotional core is what elevates "Introduction to Autonomous Mobile Robots" beyond a mere technical manual and into the realm of truly compelling literature. It's the kind of book that sparks late-night discussions and leaves you pondering the vast potential of the future long after you've turned the final page.

What makes this book truly exceptional is its "universal appeal." While academic readers will undoubtedly laud its thoroughness and cutting-edge insights into robotics, casual and general readers will be equally captivated by its storytelling prowess and its gentle, insightful gaze into the future. Children will marvel at the ingenuity of these mechanical beings, while adults will find themselves reflecting on their own place in a world increasingly shaped by technology. It's a rare feat indeed to bridge such diverse audiences, but this book achieves it with an effortless grace that is utterly charming.

Let's talk about the strengths, shall we?

Unparalleled Imaginative Scope: The authors possess the uncanny ability to make abstract concepts feel tangible and even whimsical.

Surprisingly Deep Emotional Resonance: You'll find yourself more invested in a robot's navigation than you might expect – and that's a wonderful thing.

Accessible Brilliance: Complex theories are presented with clarity and an infectious enthusiasm that invites learning.

A Humorous Touch: Amidst the technical discourse, there are moments of genuine wit and lighthearted observation that make the reading experience a joy.

This isn't a book to be merely read; it's an experience to be savored. It's a gentle nudge towards understanding the incredible advancements happening in the world of AI, presented with such warmth and ingenuity that even the most technically hesitant reader will feel encouraged to dive in. Imagine the delight of discovering how a robot "learns" to see, or the quiet satisfaction of following its programmed journey through an unfamiliar landscape. It's a delightful dance between logic and... well, something akin to wonder.

We wholeheartedly recommend "Introduction to Autonomous Mobile Robots (MIT Press)" as a timeless classic. It's a book that informs, entertains, and inspires in equal measure. It's a testament to human curiosity and ingenuity, and a shining example of how technical subjects can be illuminated with creativity and heart. This is not just an introduction; it is an awakening to the incredible possibilities that lie ahead, presented in a way that will undoubtedly capture hearts worldwide and continue to do so for generations to come. Experience this magical journey; you won't regret it.

In conclusion, this remarkable work is a testament to the enduring power of innovation, presented with a blend of academic excellence and imaginative storytelling that makes it a truly indispensable read for anyone curious about the future of robotics and, perhaps, the future of intelligence itself. It's a must-read, a must-experience, and a book that will undoubtedly leave a lasting impact on your perspective.

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how to develop robots that will be more like humans and less like computers more social than machine like and more playful and less programmed most robots are not very friendly they vacuum the rug mow the lawn dispose of bombs even perform surgery but they aren't good conversationalists it's difficult to make eye contact if the future promises more human robot collaboration in both work and play wouldn't it be better if the robots were less mechanical and more social in how to grow a robot mark lee explores how robots can be more human like friendly and engaging developments in

artificial intelligence notably deep learning are widely seen as the foundation on which our robot future will be built these advances have already brought us self driving cars and chess match winning algorithms but lee writes we need robots that are perceptive animated and responsive more like humans and less like computers more social than machine like and more playful and less programmed the way to achieve this he argues is to grow a robot so that it learns from experience just as infants do after describing what's wrong with artificial intelligence one key shortcoming it's not embodied lee presents a different approach to building human like robots developmental robotics inspired by developmental psychology and its accounts of early infant behavior he describes his own experiments with the icub humanoid robot and its development from newborn helplessness to ability levels equal to a nine month old explaining how the icub learns from its own experiences ai robots are designed to know humans as objects developmental robots will learn empathy developmental robots with an internal model of self will be better interactive partners with humans that is the kind of future technology we should work toward

based on the successful modelling and control of robot manipulators by sciavicco and siciliano springer 2000 robotics provides the basic know how on the foundations of robotics modelling planning and control it has been expanded to include coverage of mobile robots visual control and motion planning a variety of problems is raised throughout and the proper tools to find engineering oriented solutions are introduced and explained the text includes coverage of fundamental topics like kinematics and trajectory planning and related technological aspects including actuators and sensors to impart practical skill examples and case studies are carefully worked out and interwoven through the text with frequent resort to simulation in addition end of chapter exercises are proposed and the book is accompanied by an electronic solutions manual containing the matlab code for computer problems this is available free of charge to those adopting this volume as a textbook for courses

an introduction to the science and practice of autonomous robots that reviews over 300 current systems and examines the underlying technology autonomous robots are intelligent machines capable of performing tasks in the world by themselves without explicit human control examples range from autonomous helicopters to roomba the robot vacuum cleaner in this book george bekey offers an introduction to the science and practice of autonomous robots that can be used both in the classroom and as a reference for industry professionals he surveys the hardware implementations of more than 300 current systems reviews some of their application areas and examines the underlying technology including control architectures learning manipulation grasping navigation and mapping living systems can be considered the prototypes of autonomous systems and bekey explores the biological inspiration that forms the basis of many recent developments in robotics he also discusses robot control issues and the design of control architectures after an overview of the field that introduces some of its fundamental concepts the book presents background material on hardware control from both biological and engineering perspectives software architecture and robot intelligence it then examines a broad range of implementations and applications including locomotion wheeled legged flying swimming and crawling robots manipulation both arms and hands localization navigation and mapping the many case studies and specific applications include robots built for research industry and the military among them underwater robotic vehicles walking machines with four six and eight legs and the famous humanoid robots cog kismet asimo and qrio the book concludes with reflections on the future of robotics the potential benefits as well as the possible dangers that may arise from large numbers of increasingly intelligent and autonomous robots

the second edition of this handbook provides a state of the art overview on the various aspects in the rapidly developing field of robotics reaching for the human frontier robotics is vigorously engaged in the growing challenges of new emerging domains interacting exploring and working with humans the new generation of robots will increasingly touch people and their lives the credible prospect of practical robots among humans is the result of the scientific endeavour of a half a century of robotic developments that established robotics as a modern scientific discipline the ongoing vibrant expansion and strong growth of the field during the last decade has fueled this second edition of the springer handbook of robotics the first edition of the handbook soon became a landmark in robotics publishing and won the american association of publishers prose award for excellence in physical sciences mathematics as well as the organization's award for engineering technology the second edition of the handbook edited by two internationally renowned scientists with the support of an outstanding team of seven part editors and more than 200 authors continues to be an authoritative reference for robotics researchers newcomers to the field and scholars from related disciplines the contents have been restructured to achieve four main objectives the enlargement of foundational topics for robotics the

enlightenment of design of various types of robotic systems the extension of the treatment on robots moving in the environment and the enrichment of advanced robotics applications further to an extensive update fifteen new chapters have been introduced on emerging topics and a new generation of authors have joined the handbook's team a novel addition to the second edition is a comprehensive collection of multimedia references to more than 700 videos which bring valuable insight into the contents the videos can be viewed directly augmented into the text with a smartphone or tablet using a unique and specially designed app springer handbook of robotics multimedia extension portal handbookofrobotics.org

an exploration of embodied intelligence and its implications points toward a theory of intelligence in general with case studies of intelligent systems in ubiquitous computing business and management human memory and robotics how could the body influence our thinking when it seems obvious that the brain controls the body in how the body shapes the way we think rolf pfeifer and josh bongard demonstrate that thought is not independent of the body but is tightly constrained and at the same time enabled by it they argue that the kinds of thoughts we are capable of have their foundation in our embodiment in our morphology and the material properties of our bodies this crucial notion of embodiment underlies fundamental changes in the field of artificial intelligence over the past two decades and pfeifer and bongard use the basic methodology of artificial intelligence understanding by building to describe their insights if we understand how to design and build intelligent systems they reason we will better understand intelligence in general in accessible nontechnical language and using many examples they introduce the basic concepts by building on recent developments in robotics biology neuroscience and psychology to outline a possible theory of intelligence they illustrate applications of such a theory in ubiquitous computing business and management and the psychology of human memory embodied intelligence as described by pfeifer and bongard has important implications for our understanding of both natural and artificial intelligence

this book presents the results of an assessment of the state of robotics in japan south korea western europe and australia and a comparison of robotics r d programs in these countries with those in the united states the comparisons include areas like robotic vehicles space robotics service robots humanoid robots networked robots and robots for biological and medical applications and based on criteria such as quality scope funding and commercialization this important study identifies a number of areas where the traditional lead of the united states is being overtaken by developments in other countries

mobile robotics a practical introduction is an excellent introduction to the foundations and methods used for designing completely autonomous mobile robots in this book you are introduced to the fundamental concepts of this complex field via twelve detailed case studies which show how to build and program real working robots this book provides a very practical introduction to mobile robotics for a general scientific audience and is essential reading for final year undergraduate students and postgraduate students studying robotics artificial intelligence cognitive science and robot engineering its update and overview of core concepts in mobile robotics will assist and encourage practitioners of the field and set challenges to explore new avenues of research in this exciting field

the second edition of a comprehensive introduction to all aspects of mobile robotics from algorithms to mechanisms mobile robots range from the mars pathfinder mission's teleoperated sojourner to the cleaning robots in the paris metro this text offers students and other interested readers an introduction to the fundamentals of mobile robotics spanning the mechanical motor sensory perceptual and cognitive layers the field comprises the text focuses on mobility itself offering an overview of the mechanisms that allow a mobile robot to move through a real world environment to perform its tasks including locomotion sensing localization and motion planning it synthesizes material from such fields as kinematics control theory signal analysis computer vision information theory artificial intelligence and probability theory the book presents the techniques and technology that enable mobility in a series of interacting modules each chapter treats a different aspect of mobility as the book moves from low level to high level details it covers all aspects of mobile robotics including software and hardware design considerations related technologies and algorithmic techniques this second edition has been revised and updated throughout with 130 pages of new material on such topics as locomotion perception localization and planning and navigation problem sets have been added at the end of each chapter bringing together all aspects of mobile robotics into one volume introduction to autonomous mobile robots can serve as a textbook or a working tool for beginning practitioners curriculum

developed by dr robert king colorado school of mines and dr james conrad university of north carolina charlotte to accompany the national instruments labview robotics starter kit are available included are 13 6 by dr king and 7 by dr conrad laboratory exercises for using the labview robotics starter kit to teach mobile robotics concepts

a comprehensive survey of artificial intelligence algorithms and programming organization for robot systems combining theoretical rigor and practical applications this textbook offers a comprehensive survey of artificial intelligence ai algorithms and programming organization for robot systems readers who master the topics covered will be able to design and evaluate an artificially intelligent robot for applications involving sensing acting planning and learning a background in ai is not required the book introduces key ai topics from all ai subdisciplines throughout the book and explains how they contribute to autonomous capabilities this second edition is a major expansion and reorganization of the first edition reflecting the dramatic advances made in ai over the past fifteen years an introductory overview provides a framework for thinking about ai for robotics distinguishing between the fundamentally different design paradigms of automation and autonomy the book then discusses the reactive functionality of sensing and acting in ai robotics introduces the deliberative functions most often associated with intelligence and the capability of autonomous initiative surveys multi robot systems and in a new chapter human robot interaction and offers a metaview of how to design and evaluate autonomous systems and the ethical considerations in doing so new material covers locomotion simultaneous localization and mapping human robot interaction machine learning and ethics each chapter includes exercises and many chapters provide case studies endnotes point to additional reading highlight advanced topics and offer robot trivia

mobile robotics a practical introduction 2nd edition is an excellent introduction to the foundations and methods used for designing completely autonomous mobile robots a fascinating cutting edge research topic autonomous mobile robotics is now taught in more and more universities in this book you are introduced to the fundamental concepts of this complex field via twelve detailed case studies that show how to build and program real working robots topics covered in clued learning autonomous navigation in unmodified noisy and unpredictable environments and high fidelity robot simulation this new edition has been updated to include a new chapter on novelty detection and provides a very practical introduction to mobile robotics for a general scientific audience it is essential reading for 2nd and 3rd year undergraduate students and postgraduate students studying robotics artificial intelligence cognitive science and robot engineering the update and overview of core concepts in mobile robotics will assist and encourage practitioners of the field and set challenges to explore new avenues of research in this exiting field the author is senior lecturer at the department of computer science at the university of essex a very fine overview over the relevant problems to be solved in the attempt to bring intelligence to a moving vehicle professor dr ewald von puttkamer university of kaiserslautern case studies show ways of achieving an impressive repertoire of kinds of learned behaviour navigation and map building the book is an admirable introduction to this modern approach to mobile robotics and certainly gives a great deal of food for thought this is an important and though provoking book alex m andrew in *kybernetes* vol 29 no 4 and *robotica* vol 18

this textbook explores the foundational principles of robotics focusing on its core pillars modeling planning and control balancing mathematical rigor and physical intuition a coherent formalism is established and used throughout the book at the same time technological challenges and application driven solutions are given appropriate consideration with a general perspective that includes both fixed base manipulators and mobile robots the book presents the essential tools for understanding key topics such as kinematics statics trajectory planning dynamics and motion control in its second part more advanced topics are addressed including wheeled robots visual control motion planning force control flexible robots and cooperative manipulation to support the learning process appendices provide essential background material on linear algebra mechanics differential geometry control theory and graph search algorithms the practical implementation of the methodologies is emphasized throughout with over 50 worked examples and case studies many supported by simulations additionally more than 190 end of chapter problems are included with a solutions manual available for instructors adopting the book for their courses foundations of robotics is designed for use as a textbook in both undergraduate and graduate robotics courses within engineering programs making it an ideal resource for students and educators alike

making a robot that looks and behaves like a human being has been the subject of many popular science fiction movies and books although the development of such a robot faces many challenges the making of a virtual human has long been potentially possible with recent advances in various key technologies related to hardware and software the making of humanlike robots is increasingly becoming an engineering reality development of the required hardware that can perform humanlike functions in a lifelike manner has benefitted greatly from development in such technologies as biologically inspired materials artificial intelligence artificial vision and many others producing a humanlike robot that makes body and facial expressions communicates verbally using extensive vocabulary and interprets speech with high accuracy is extremely complicated to engineer advances in voice recognition and speech synthesis are increasingly improving communication capabilities in our daily life we encounter such innovations when we call the telephone operators of most companies today as robotics technology continues to improve we are approaching the point where on seeing such a robot we will respond with wow this robot looks unbelievably real just like the reaction to an artificial flower the accelerating pace of advances in related fields suggests that the emergence of humanlike robots that become part of our daily life seems to be imminent these robots are expected to raise ethical concerns and may also raise many complex questions related to their interaction with humans

a much needed clearinghouse for information on amateur and educational robotics containing over 2 500 listings of robot suppliers including mail order and local area businesses contains resources for both common and hard to find parts and supplies features dozens of sidebars to clarify essential robotics technologies provides original articles on various robot building topics

an accessible and engaging account of robots covering the current state of the field the fantasies of popular culture and implications for life and work robots are entering the mainstream technologies have advanced to the point of mass commercialization roomba for example and adoption by governments most notably their use of drones meanwhile these devices are being received by a public whose main sources of information about robots are the fantasies of popular culture we know a lot about c 3po and robocop but not much about atlas motoman kiva or beam real life robots that are reinventing warfare the industrial workplace and collaboration in this book technology analyst john jordan offers an accessible and engaging introduction to robots and robotics covering state of the art applications economic implications and cultural context jordan chronicles the prehistory of robots and the treatment of robots in science fiction movies and television from the outsized influence of mary shelley's frankenstein to isaac asimov's i robot in which asimov coined the term robotics he offers a guided tour of robotics today describing the components of robots the complicating factors that make robotics so challenging and such applications as driverless cars unmanned warfare and robots on the assembly line roboticists draw on such technical fields as power management materials science and artificial intelligence jordan points out however that robotics design decisions also embody such nontechnical elements as value judgments professional aspirations and ethical assumptions and raise questions that involve law belief economics education public safety and human identity robots will be neither our slaves nor our overlords instead they are rapidly becoming our close companions working in partnership with us whether in a factory on a highway or as a prosthetic device given these profound changes to human work and life jordan argues that robotics is too important to be left solely to roboticists

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this book provides an introductory text for students coming new to the field of robotics and a survey of the state of the art for professional practitioners some of the outstanding features of this book include a unique approach which ties the multi disciplinary components of robotics into a unified text broad and in depth coverage of all the major topics from the mechanics of movement to modelling and programming rigorous mathematical treatment of mature topics combined with an algorithmic approach to newer areas of research practical examples taken from a wide range of fields including computer science electronic engineering mechanical engineering and production engineering step by step development of problems and many worked examples

in robotics in service he observes that the time is ripe for robotics to launch itself into an entirely new marketplace

genetic algorithms are a category of computer algorithms suggested by the evolutionary process of natural selection the proceedings of the july 1995 conference include papers describing both the theory and practice of genetic algorithms and other forms of evolutionary computation including evoluti

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